

Lecture 6

Connections

How Do we differentiate vector fields with Respect to Each other in $\mathbb{R}^n$?

Vector fields $X, Y: \mathbb{R}^n \rightarrow \mathbb{R}^n$ are n -tuples of functions $a_i, b_j: \mathbb{R}^n \rightarrow \mathbb{R}$

$$X = a_1 \frac{\partial}{\partial x_1} + a_2 \frac{\partial}{\partial x_2} + \dots + a_n \frac{\partial}{\partial x_n}$$

$$Y = b_1 \frac{\partial}{\partial x_1} + b_2 \frac{\partial}{\partial x_2} + \dots + b_n \frac{\partial}{\partial x_n}$$

Here we
(are identifying
 $T_p \mathbb{R}^n \cong \mathbb{R}^n$
possible
because
 $\mathbb{R}^n$ is vector space)

AND Each b_j can be differentiated at $p \in \mathbb{R}^n$ in direction $X(p)$

$$(X(b_j))_p = a_1(p) \frac{\partial b_j}{\partial x_1}(p) + \dots + a_n(p) \frac{\partial b_j}{\partial x_n}(p) = \sum_i a_i(p) \frac{\partial b_j}{\partial x_i}(p)$$

$$\downarrow \nabla_X Y \uparrow (dY)(X) = X(Y) = \sum_j \left(\sum_i a_i \frac{\partial b_j}{\partial x_i} \right) \frac{\partial}{\partial x_j}$$

ON A Manifold v.f are sections of TM so $X, Y: M \rightarrow TM$
so $dY(p): T_p M \rightarrow T_{Y(p)} TM$

so $dY(X)$ would land on $T(TM)$ Not TM

$M = \mathbb{R}^n \rightarrow T\mathbb{R}^n = \mathbb{R}^n \times \mathbb{R}^n$ Then

$$dY: T\mathbb{R}^n \rightarrow T(T\mathbb{R}^n) \cong (\mathbb{R}^n \times \mathbb{R}^n) \times (\mathbb{R}^n \times \mathbb{R}^n)$$

$$(p, v) \mapsto ((p, Y(p)), (Y(p), dY_p(v)))$$

Canonical Horz
For $T(TM) \rightarrow TM$ is $M =$

$$T_p(TM) = T_p^* \oplus V$$

$$TE = H^\nabla \oplus \cancel{VE} \leftarrow \text{Determine proj on } V \text{ along } H^\nabla$$

vector BUNDLE.

Idea $\pi: E \rightarrow M \quad \pi_*: TE \rightarrow TM$

Vertical tangent space
 V is $\text{Ker}(\pi_*)$

Rmk On A Manifold we can choose coordinates dist. Near a point and compute derivatives of $v.f.$ in $\mathbb{R}^n$ but this would depend on the choice of coordinates (charts)

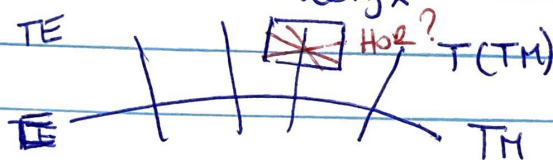
Can't define

Not same vector space

can't identify

$$dY(X)_p = \lim_{q \rightarrow p \text{ along } X} \frac{Y(q) - Y(p)}{\text{dist}(p,q)}$$

$T_p M$ and $T_q M$ in a canonical way.



Def A connection ∇ on A vector bundle $E \rightarrow M$ is A Map

$$\nabla: \mathcal{X}(M) \times \Gamma(E) \rightarrow \Gamma(E)$$

$$(X, Y) \mapsto \nabla_X Y \quad \text{st.}$$

1) $X \mapsto \nabla_X Y$ is $C^\infty(M)$ -linear

$$\nabla_{f_1 X_1 + f_2 X_2} Y = f_1 \nabla_{X_1} Y + f_2 \nabla_{X_2} Y \quad \forall f_i \in C^\infty$$

2) $Y \mapsto \nabla_X Y$ is $\mathbb{R}$ -linear $\nabla_X (c_1 Y_1 + c_2 Y_2) = c_1 \nabla_X Y_1 + c_2 \nabla_X Y_2$
 $\forall c_i \in \mathbb{R}$.

3) Leibniz Rule $\nabla_X (fY) = f \nabla_X Y + X(f) Y$.

Note Using partitions of unity we can show that

Every vector bundle $E \rightarrow M$ can be endowed with A connection ($dY(X) = \nabla_X Y$ is A connection on $T\mathbb{R}^n \rightarrow \mathbb{R}^n$).

Let's specialize to $E = TM$ so $\nabla: \mathcal{X}(M) \times \mathcal{X}(M) \rightarrow \mathcal{X}(M)$
 On a chart using coordinate vectors $\left\{ \frac{\partial}{\partial x_1}, \dots, \frac{\partial}{\partial x_n} \right\}$

$$\nabla_{\frac{\partial}{\partial x_i}} \frac{\partial}{\partial x_j} = \sum_{k=1}^n \Gamma_{ij}^k \frac{\partial}{\partial x_k}$$

called "Christoffel symbols" of ∇ .

(Note that $\Gamma_{ij}^k = \Gamma_{ji}^k$ because $\left[\frac{\partial}{\partial x_i}, \frac{\partial}{\partial x_j} \right] = 0$ No Torsion)

Then if $X = \sum a_i \frac{\partial}{\partial x_i}$ and $Y = \sum b_j \frac{\partial}{\partial x_j}$ on U

we have $\nabla_X Y = \nabla_{\sum a_i \frac{\partial}{\partial x_i}} \left(\sum b_j \frac{\partial}{\partial x_j} \right) = \sum_i a_i \nabla_{\frac{\partial}{\partial x_i}} \left(\sum b_j \frac{\partial}{\partial x_j} \right)$

$$= \sum_{i,j} a_i b_j \nabla_{\frac{\partial}{\partial x_i}} \frac{\partial}{\partial x_j} + \sum_{i,j} a_i \frac{\partial b_j}{\partial x_i} \frac{\partial}{\partial x_j}$$

$$\underbrace{\sum_k \Gamma_{ij}^k \frac{\partial}{\partial x_k}}_{\text{This is "X(Y)" in coordinates of } \nabla \text{ in } \mathbb{R}^n} \quad \underbrace{X(b_j) \frac{\partial}{\partial x_j}}_{\text{this is connection to make coordinates invariant.}} \quad \text{as in } \mathbb{R}^n$$

$$= \sum_{i,j,k} \left[a_i \frac{\partial b_k}{\partial x_i} + \sum_j a_i b_j \Gamma_{ij}^k \right] \frac{\partial}{\partial x_k}$$

This is "X(Y)"
in coordinates
of ∇ in $\mathbb{R}^n$

this is
connection
to make
coordinates
invariant.

(in $\mathbb{R}^n$, the usual ∇ has $\Gamma_{ij}^k = 0$ so $\nabla_X Y = X(Y)$)

Note 1 $(\nabla_X Y)_p$ only depends on $a_i(p)$ and b_j near p .

Note 2 From ∇ we defined Γ_{ij}^k

Conversely given Γ_{ij}^k we can define

A unique connection with these prescribed Christoffel symbols (in charts by formula above)

Lecture 7

IF ∇ and $\tilde{\nabla}$ are connections on TM with Christoffel symbols Γ and $\tilde{\Gamma}$ then

$A = \nabla - \tilde{\nabla}$ is a $(1,2)$ -tensor $A_{ij}^k = \Gamma_{ij}^k - \tilde{\Gamma}_{ij}^k$
where $A \in \Gamma(T^*M \otimes T^*M \otimes TM)$

The space of connections on TM is therefore an Affine space $\{\nabla + A\}$
 $\uparrow$
Fixed connection

Proof

Check A is C^∞ -LINEAR.

$$A_X(fY) = \nabla_X(fY) - \tilde{\nabla}_X(fY) = f(A_X Y)$$

Remark From A connection ∇ on TM we can define induced connections on T^*M or Any tensor power $\otimes^p TM \otimes \otimes^q T^*M$ in particular on p -Forms

$$1\text{-Form } \omega : (\nabla_X \omega)(Y) = X(\omega(Y)) - \omega(\nabla_X Y) \quad \forall X, Y$$

$$T \in \Gamma((T^*M)^{\otimes r} \otimes (TM)^{\otimes s}) \quad \nabla T \in \Gamma((T^*M)^{\otimes r+1} \otimes (TM)^{\otimes s})$$

$$X(Y_1, \dots, Y_r, \omega_1, \dots, \omega_s) = X \cdot (T(Y_1, \dots, Y_r, \omega_1, \dots, \omega_s))$$

$$- \sum_{k=1}^r T(Y_1, \dots, \nabla_X Y_k, \dots, Y_r, \omega_1, \dots, \omega_s)$$

$$- \sum_{k=1}^s T(Y_1, \dots, Y_r, \omega_1, \dots, \nabla_X \omega_k, \dots, \omega_s)$$

$$\text{Rmk } f^*E = \{(m, e) \in M \times E \mid f(m) = \pi(e)\} \subseteq M \times E$$

Def Given a connection ∇ on $E \xrightarrow{\pi} N$ and a smooth map $f: M \rightarrow N$ the pullback connection $f^*\nabla$ on $f^*E \rightarrow M$ is determined by

$$(f^*\nabla)_x(f^*s) = f^*(\nabla_{df(x)} s) \quad s \in \Gamma(E)$$

Important Example

Let $\gamma: (a, b) \rightarrow M$ be a smooth curve in M and γ^*TM be pullback bundle

The vector bundle over (a, b) whose sections $V \in \Gamma(\gamma^*TM)$ are vector fields along γ .

$$V: (a, b) \rightarrow TM \text{ st. } V(t) \in T_{\gamma(t)}M \quad \forall t \in (a, b)$$

Examples ① $\dot{\gamma}(t) \in \Gamma(\gamma^*TM)$ is a vector field along γ

← which may not be the Restriction of an ambient V.F.

② Restrict an Ambient v.f. to γ

Given a connection on TM we use the pullback connection $\gamma^*\nabla$ to define the covariant derivative of V.f. along γ :

$$V \in \Gamma(\gamma^*TM) \rightsquigarrow \frac{D}{dt} V := (\gamma^*\nabla)_{\partial/\partial t} V \in \Gamma(\gamma^*TM)$$

satisfying following properties:

$$\bullet \frac{D}{dt}(c_1 V_1 + c_2 V_2) = c_1 \frac{D}{dt} V_1 + c_2 \frac{D}{dt} V_2 \quad \forall c_1, c_2 \in \mathbb{R}$$

$$\bullet \frac{D}{dt}(fV) = f'V + f \cdot \frac{D}{dt} V \quad \forall f \in C^\infty([a,b] \rightarrow \mathbb{R})$$

$$\bullet \text{ If } V \text{ is the Restriction of An ambient V.F } \tilde{V} \text{ on } M$$

then $\frac{D}{dt} V = \nabla_{\dot{\gamma}(t)} \tilde{V} \quad \left((\gamma^* \nabla)_{\frac{\partial}{\partial t}} V = \nabla_{\dot{\gamma}(\frac{\partial}{\partial t})} \tilde{V} \right)$ where $V = \gamma^* \tilde{V}$

In coordinates with $\nabla_{\frac{\partial}{\partial x_i}} \frac{\partial}{\partial x_j} = \sum_k \Gamma_{ij}^k \frac{\partial}{\partial x_k}$ we have

that A V.f along γ say $V \in \Gamma(\gamma^* TM)$ can be written

as: $V(t) = \sum_{j=1}^n v_j(t) \frac{\partial}{\partial x_j} \Big|_{\gamma(t)}$ For some Functions $v_j: (a,b) \rightarrow \mathbb{R}$

$$\frac{D}{dt} V(t) = \sum_j v_j'(t) \frac{\partial}{\partial x_j} \Big|_{\gamma(t)} + v_j(t) \frac{D}{dt} \left(\frac{\partial}{\partial x_j} \Big|_{\gamma(t)} \right)$$

$\nabla_{\dot{\gamma}(t)} \frac{\partial}{\partial x_j}$ because $\frac{\partial}{\partial x_j} \Big|_{\gamma(t)}$ is Restriction of $\frac{\partial}{\partial x_j}$

$$= \sum_j v_j'(t) \frac{\partial}{\partial x_j} \Big|_{\gamma(t)} + \sum_{i,j,k} a_i'(t) v_j(t) \Gamma_{ij}^k(\gamma(t)) \frac{\partial}{\partial x_k} \Big|_{\gamma(t)}$$

write $\gamma(t)$ in coordinates

$$\gamma(t) = (a_i(t)) \text{ so}$$

$$\dot{\gamma}(t) = \sum a_i'(t) \frac{\partial}{\partial x_i} \Big|_{\gamma(t)}$$

and hence

$$\nabla_{\dot{\gamma}(t)} \frac{\partial}{\partial x_j} = \sum a_i'(t) \nabla_{\frac{\partial}{\partial x_i}} \frac{\partial}{\partial x_j} = \sum a_i'(t) \Gamma_{ij}^k \frac{\partial}{\partial x_k}$$

$$= \sum_k \left(v_k' + \sum_{i,j} a_i' v_j \Gamma_{ij}^k \right) \frac{\partial}{\partial x_k} \Big|_{\gamma(t)}$$

coefficients of $\frac{DV}{dt}$ as A v.f along γ

covariant derivative along γ
 $\downarrow$

A v.f. V along γ is parallel if $\frac{D}{dt}V = 0$
 (similarly for any tensor along γ)

OP Given a (piecewise) smooth curve $\gamma: (a, b) \rightarrow M$
 a connection on TM and a vector $v \in T_{\gamma(t_0)}M$
 For $t_0 \in (a, b)$ there exists a unique parallel v.f.
 $V: (a, b) \rightarrow TM$ along γ s.t. $V(t_0) = v$
 Moreover $V(t)$ depends smoothly on the initial data v .

E Existence uniqueness and smooth dependence on initial data
 For 1st order linear ODE system: (Picard Lindelöf)

$$\begin{cases} V'_k(t) + \sum_{i,j} a_{ij}^k(t) v_j(t) \Gamma_{ij}^k(\gamma(t)) = 0 & k=1, \dots, n \\ V_k(t_0) = v_k \end{cases}$$

$\nwarrow$ coefficient of $\dot{\gamma}$

The above $V(t)$ is called **parallel transport** wrt ∇
 of $v \in T_{\gamma(t_0)}M$ along γ .

te In $\mathbb{R}^n$ wrt $\nabla_X Y = X(Y)$ parallel transport is constant
 and independent of path.

Def Let M be a smooth manifold and ∇ be connection on TM .
A curve $\gamma: (a,b) \rightarrow M$ is a ∇ -geodesic in M if $\nabla_{\dot{\gamma}} \dot{\gamma} = 0$.

In coordinates if $V = \dot{\gamma}(t) = \sum a_i(t) \frac{\partial}{\partial x_i} \Big|_{\gamma(t)}$ then

$$\nabla_{\dot{\gamma}} \dot{\gamma} = \sum_k a_k''(t) \frac{\partial}{\partial x_k} \Big|_{\gamma(t)} + \sum_{i,j} a_i'(t) a_j'(t) \Gamma_{ij}^k(\gamma(t)) \frac{\partial}{\partial x_k} \Big|_{\gamma(t)}.$$

so $\gamma(t) = (a_1(t), \dots, a_n(t))$ is ∇ -geodesic iff.

$$a_k'' + \sum_{i,j} a_i' a_j' \Gamma_{ij}^k = 0 \quad k=1, \dots, n$$

2nd ORDER
quasi-linear
ODE.

→ **Ex** sphere $\gamma(t)^T \gamma(t) = 1 \Rightarrow \gamma^T \dot{\gamma} + \dot{\gamma}^T \gamma = 0$ so $\dot{\gamma}$ is not tangent "the acceleration"
or $\gamma^T \ddot{\gamma} = 0 \Rightarrow \gamma^T [\ddot{\gamma} + \gamma \dot{\gamma}^T \ddot{\gamma}] = 0$

Prop Given $p \in M$ and $v \in T_p M$ and a connection ∇ on $TM \ni \exists!$ maximal (Domain can't be extended) ∇ -geodesic $\gamma: I \rightarrow M$ with $t_0 \in I$ and $\gamma(t_0) = p$, $\dot{\gamma}(t_0) = v$ which depends smoothly on $(p, v) \in TM$.

Proof Existence uniqueness and smooth dependence for second order ODE.

Notes