

Lecture 12

(M, g) Riemannian D^g its Levi-Civita connection

The curvature of D^g is the (1,3)-tensor

$$R: TM \otimes TM \otimes TM \rightarrow TM$$

$$\ominus R^g_{X,Y}Z = D^g_X(D^g_Y Z) - D^g_Y(D^g_X Z) - D^g_{[X,Y]}Z$$

Define (0,4)-tensor

$$R^g(X, Y, Z, W) = g(R^g_{X,Y}Z, W) \text{ then}$$

(so $R^g(fX, Y, Z, W) = f R^g(X, Y, Z, W)$ etc.)

$$\textcircled{1} R^g(X, Y, Z, W) = -R^g(Y, X, Z, W) = -R^g(X, Y, W, Z)$$

$\uparrow$
 $D^g g = 0$

$$\textcircled{2} R^g(X, Y, Z, W) = R^g(Z, W, X, Y)$$

$\uparrow$
 D^g has No torsion

$\textcircled{3}$ 1st Bianchi identity $\hookleftarrow$

$$R^g(X, Y, Z, W) + R^g(Y, Z, X, W) + R^g(Z, X, Y, W) = 0$$

$\textcircled{3}$ Uses Jacobi identity ~~$[X, Y], Z$~~ + ~~$[Y, Z], X$~~ + ~~$[Z, X], Y$~~

$$[X, [Y, Z]] + [Y, [Z, X]] + [Z, [X, Y]] = 0$$

Indeed

$$R^g(X, Y, Z, W) + R^g(Y, Z, X, W) + R^g(Z, X, Y, W)$$

$$\rightarrow = -g([X, [Y, Z]] + [Y, [Z, X]] + [Z, [X, Y]], W) = 0$$

② Follows From ① + ③

$$\begin{aligned}
 R^g(X, Y, Z, W) &= -R^g(Y, Z, X, W) - R^g(Z, X, Y, W) \\
 &= R^g(Y, Z, W, X) + R^g(Z, X, W, Y) \\
 \textcircled{3} &= -R^g(Z, W, Y, X) - R^g(W, Y, Z, X) \\
 &\quad - R^g(X, W, Z, Y) - R^g(W, Z, X, Y) \\
 &= 2R^g(Z, W, X, Y) + R^g(W, Y, X, Z) \\
 &\quad + R^g(X, W, Y, Z) \\
 \textcircled{3} &\Rightarrow = 2R^g(Z, W, X, Y) - R^g(Y, X, W, Z)
 \end{aligned}$$

We can think of R as Asymmetric Endomorphism (bilinear form)
 $R^g: \Lambda^2 TM \rightarrow \Lambda^2 TM$ called curvature operator.

lem 2

IN NORMAL coordinates:

$$\begin{aligned}
 g_{ij}(x) &= \delta_{ij} + \frac{1}{3} R_{ikjl}(p) x_k x_l \\
 &\quad + o(|x|^3)
 \end{aligned}$$

Curvature
 Measures deviation
 From Euclidean
 metric.

Rem 1 R^g can be Expressed in terms of Christoffel symbols.

Def The sectional curvature of plane π spanned by X, Y

$$\text{Sec}(X, Y) = \frac{R^g(X, Y, X, Y)}{g(X, Y, X, Y)} = \frac{R^g(X, Y, X, Y)}{\|X\|^2 \|Y\|^2 - g(X, Y)^2}$$

Note: IF $\text{span}\{X, Y\} = \text{span}\{X', Y'\}$ then
 $\text{Sec}(X, Y) = \text{Sec}(X', Y')$

Prop The sectional curvature determines
 The curvature operator.

Proof Suppose R' such that $\exists \frac{R'(X,Y)X,Y}{\text{Sec} \uparrow \text{of } R' \|X \wedge Y\|^2}$ show $R' = R$

By Hypothesis

$$\cancel{R'(X+Z, Y, X+Z)} = \cancel{R(X+Z, Y, X+Z)}$$

$$R'(X+Z, Y, X+Z, Y) = R'(X+Z, Y, X+Z, Y)$$

so

$$R(X, Y, X, Y) + 2R'(X, Y, Z, Y) + R'(Z, Y, Z, Y)$$

$$= R(X, Y, X, Y) + 2R(X, Y, Z, Y) + R(Z, Y, Z, Y)$$

$$\Rightarrow R'(X, Y, Z, Y) = R(X, Y, Z, Y) (*)$$

$$\Rightarrow R'(X, Y+W, Z, Y+W) = R(X, Y+W, Z, Y+W)$$

$$\Rightarrow R'(X, Y, Z, Y) + R'(X, Y, Z, W) + R'(X, W, Z, Y) + R'(X, W, Z, W)$$

using (*) $= R(X, Y, Z, Y) + R(X, Y, Z, W) + R(X, W, Z, Y) + R(X, W, Z, W)$

$$\Rightarrow R'(X, Y, Z, W) + R'(X, W, Z, Y)$$

$$= R(X, Y, Z, W) + R(X, W, Z, Y)$$

$$\hookrightarrow R'(X, Y, Z, W) - R(X, Y, Z, W) = -R'(X, W, Z, Y) + R(X, W, Z, Y)$$

$$= \cancel{R'(W, X, Z, Y)} - \cancel{R(W, X, Z, Y)}$$

$$\Rightarrow -R'(X, Y, W, Z) + R(X, Y, W, Z) = R'(X, W, Y, Z) - R(X, W, Y, Z)$$

$$(*) \Rightarrow R'(X, Y, W, Z) - R(X, Y, W, Z) = R'(W, X, Y, Z) - R(W, X, Y, Z)$$

1st Bianchi Identity $\Rightarrow (R' - R)(X, Y, Z)$ is invariant By cyclic permutation

$$+ R'(Y, W, X, Z) + R'(W, X, Y, Z) - R(Y, W, X, Z) - R(W, X, Y, Z)$$

$$= R'(X, W, Y, Z) - R(X, W, Y, Z) \Rightarrow 3(R' - R) = 0$$

$$R'(X, Y, W, Z) + R'(Y, W, X, Z) + R'(W, X, Y, Z) = 0$$

$$(**) \quad 2R'(X, Y, W, Z) + R'(X, Y, W, Z) = 0$$

$$\Rightarrow 3R'(Y, W, X, Z) = 3R(X, W, X, Z) \quad \forall X, Y, W, Z$$

$$R' = R$$

Rem 1 In $\dim = 2$ $R^g: \Lambda^2 TM \rightarrow \Lambda^2 TM$
is given by A scalar Function called
GAUSSIAN curvature

Proposition Schur '1886 (Proof in Kuenel Differential
Geometry: curves - Surfaces - Manifolds)
Let (M, g) be A connected Riemannian manifold.
IF $\dim M \geq 3$ and if $\sec_p(X_p, Y_p)$ Doesn't depend on plane in
 $T_p M$ but only on the point $p \in M$ then sectional curvature
is constant i.e Does Not depend on p .

* use 2nd Bianchi identity, $\sigma_{x, y, z, w}(\nabla_x R^g)(z, x, y, w) = 0$

Rem IF $\tilde{g} = \lambda g$ $\lambda > 0$ is constant $\Rightarrow$ Christoffel symbols
and Levi-Civita are unchanged ~~However~~ as well
as curvature but sectional curvature changes
 $\sec \tilde{g} = \frac{1}{\lambda} \sec g$.

IF M RIEMANNIAN OF constant sectional curvature then
up Rescaling we may assume $\sec = 0, 1, -1$.

Examples ① sectional curvature of $S^n(1) = 1$
② sectional curvature of $\mathbb{R}^n = 0$
sectional curvature Hyperbolic space is -1

Def The Riemannian Ricci curvature is a $(0,2)$ tensor
it is trace of Endomorphism ^{of $T_p M$} given by
 $v \mapsto R_p(X, v)Y$

NORMAL COOR
value element
 $\det(g_{ij}) =$

$$1 - \frac{1}{6} \text{Ric}_p(p) x_i x_i + O(|x|^3)$$

IF $\{e_i\}$ is orthonormal Basis of $T_p M$ then
 $\text{Ric}_p(X, Y) = \sum_i R^g(X, e_i, Y, e_i)$
 $\Rightarrow$ Ric is symmetric (symmetry ② of R^g)

Def The Riemannian scalar curvature is trace of Ricci curvature

$$\text{Vol}(B_r(p)) = \frac{\pi^{n/2}}{\Gamma(n/2+1)} r^n \left(1 - \frac{S_r^2}{6(n+2)} + O(r^3)\right)$$

$$S^g(p) = \sum_i \text{Ric}(e_i, e_i) = \sum_{i,j} R^g(e_j, e_i, e_j, e_i)$$

Prop IF M has constant sectional curvature $= k$ then

$$R^g(X, Y, Z, W) =$$

$$g(R^g_{X,Y} Z, W) = -K [g(Y, Z)g(X, W) - g(X, Z)g(Y, W)]$$

Proof Define $(0,4)$ -tensor

$$A(X, Y, Z, W) = -K [g(Y, Z)g(X, W) - g(X, Z)g(Y, W)]$$

A satisfies symmetry property of curvature

$$\text{But } A(X, Y, X, Y) = -K [g(X, Y)g(X, Y) - |X|^2 |Y|^2]$$

$$= R(X, Y, X, Y)$$

$$\Rightarrow A = R$$

Exercise For A Manifold with constant sectional curvature

K we have $\text{Ric} = (n-1)K g \Rightarrow$ Einstein Metric

$$\text{and } S^g = n(n-1)K$$