Definition: Let $\mathcal{B} = \{\vec{u}_1, \ldots, \vec{u}_k\}$ be a basis of a subspace S of \mathbb{R}^n (which can be all of \mathbb{R}^n), and let \vec{w} be a vector in S. The *coordinates* of \vec{w} in the basis \mathcal{B} are the k numbers a_1, a_2, \ldots, a_k such that

$$\vec{w} = a_1\vec{u}_1 + a_2\vec{u}_2 + \dots + a_k\vec{u}_k$$

NOTATION: The coordinates of a vector \vec{w} in a basis \mathcal{B} will be denoted $[\vec{w}]_{\mathcal{B}}$. **Example:** Consider the basis of \mathbb{R}^2 given by $\mathcal{B} = \left\{ \begin{pmatrix} 1 \\ 2 \end{pmatrix}, \begin{pmatrix} -1 \\ 1 \end{pmatrix} \right\}$. Then the vector \vec{w} with coordinates $[\vec{w}]_{\mathcal{B}} = (2,3)$ is

$$2\binom{1}{2} + 3\binom{-1}{1} = \binom{2-3}{4+3} = \binom{-1}{7}$$

Another example: what are the coordinates of the vector $\begin{pmatrix} 3\\5 \end{pmatrix}$ in the basis \mathcal{B} ? We would need to find x_1, x_2 such that

$$x_1 \begin{pmatrix} 1\\2 \end{pmatrix} + x_2 \begin{pmatrix} -1\\1 \end{pmatrix} = \begin{pmatrix} 3\\5 \end{pmatrix}$$

Do it as usual:

$$\begin{pmatrix} 1 & -1 & | & 3 \\ 2 & 1 & | & 5 \end{pmatrix} \longrightarrow \begin{pmatrix} 1 & -1 & | & 3 \\ 0 & 3 & | & -1 \end{pmatrix} \longrightarrow \begin{pmatrix} 1 & -1 & | & 3 \\ 0 & 1 & | & -1/3 \end{pmatrix} \longrightarrow \begin{pmatrix} 1 & 0 & | & 8/3 \\ 0 & 1 & | & -1/3 \end{pmatrix}$$

The answer is, therefore, $\begin{bmatrix} 3 \\ 5 \end{bmatrix}_{\mathcal{B}} = \begin{pmatrix} 8/3 \\ -1/3 \end{pmatrix}$. It is easy to check that this is correct:

$$\frac{8}{3} \begin{pmatrix} 1\\2 \end{pmatrix} - \frac{1}{3} \begin{pmatrix} -1\\1 \end{pmatrix} = \begin{pmatrix} 3\\5 \end{pmatrix}.$$

Exercises: Let $\mathcal{B} = \left\{ \begin{pmatrix} 1 \\ -1 \\ 1 \end{pmatrix}, \begin{pmatrix} 2 \\ 1 \\ 1 \end{pmatrix} \right\}$ be a basis of some subspace S of \mathbb{R}^3 .

• Find the vector $\vec{w} \in S \subset \mathbb{R}^3$ whose coordinates in the basis \mathcal{B} are

$$\begin{pmatrix} 5\\ -3 \end{pmatrix} \qquad \begin{pmatrix} 2\\ 1 \end{pmatrix} \qquad \begin{pmatrix} 1\\ 0 \end{pmatrix} \qquad \begin{pmatrix} 1\\ 1 \end{pmatrix}.$$

• The following vectors are in S. Find their coordinates in the basis \mathcal{B} :

$$\vec{u} = \begin{pmatrix} 3\\ 9\\ -1 \end{pmatrix}, \qquad \vec{v} = \begin{pmatrix} 7\\ -1\\ 5 \end{pmatrix}, \qquad \vec{w} = \begin{pmatrix} 2\\ 1\\ 1 \end{pmatrix}.$$

Change of coordinates between two bases of \mathbb{R}^n

Recall: The standard basis of \mathbb{R}^n is the basis st = $\{\vec{e}_1, \vec{e}_2, \dots, \vec{e}_n\}$ given by

$$\vec{e}_1 = \begin{pmatrix} 1\\0\\\vdots\\0 \end{pmatrix}, \vec{e}_2 = \begin{pmatrix} 0\\1\\\vdots\\0 \end{pmatrix}, \dots, \vec{e}_n = \begin{pmatrix} 0\\0\\\vdots\\1 \end{pmatrix}.$$

The standard basis will be denoted by "st", and the coordinates of a vector \vec{w} in the standard basis will be denoted by $[\vec{w}]_{st}$

Observation: Any vector $\vec{w} = \begin{pmatrix} a_1 \\ a_2 \\ \vdots \\ a_n \end{pmatrix}$ in \mathbb{R}^n can be written, in the standard basis, as $a_1\vec{e_1} + a_2\vec{e_2} + \dots + a_n\vec{e_n}$, so the coordinates of $\begin{pmatrix} a_1 \\ a_2 \\ \vdots \\ a_n \end{pmatrix}$ in the standard basis are just $\begin{pmatrix} a_1 \\ a_2 \\ \vdots \\ a_n \end{pmatrix}$. In other words, $[\vec{w}]_{st} = \vec{w}$.

Changing from a basis of \mathbb{R}^n to the standard basis

Suppose that the coordinates of a vector \vec{w} in the basis $\mathcal{B} = \{\vec{u}_1, \dots, \vec{u}_n\}$ of \mathbb{R}^n , are $\begin{pmatrix} a_1\\a_2\\\vdots\\a \end{pmatrix}$, that is, $[\vec{w}]_{\mathcal{B}} = \begin{pmatrix} a_1\\a_2\\\vdots\\a \end{pmatrix}$.

What are the coordinates of \vec{w} in the standard basis?

This is not hard: we have $\vec{w} = a_1\vec{u}_1 + \cdots + a_n\vec{u}_n$, and therefore by the previous observation, $[\vec{w}]_{st} = a_1\vec{u}_1 + a_2\vec{u}_2 + \cdots + a_n\vec{u}_n$. This can be written as

$$[\vec{w}]_{\rm st} = [\vec{u}_1, \vec{u}_2, \cdots \vec{u}_n] \begin{pmatrix} a_1 \\ a_2 \\ \vdots \\ a_n \end{pmatrix} = U[\vec{w}]_{\mathcal{B}}.$$

We can therefore write

$$[\vec{w}]_{\mathrm{st}} = U [\vec{w}]_{\mathcal{B}}, \text{ where } U = [\vec{u}_1, \vec{u}_2, \cdots \vec{u}_n].$$

Changing from the standard basis to another basis of \mathbb{R}^n

In view of the last equation, this is easy: multiply the last equation on both sides by U^{-1} on the left to get

$$[\vec{w}]_{\mathcal{B}} = U^{-1}[\vec{w}]_{\mathrm{st}}, \text{ where } U = [\vec{u}_1, \vec{u}_2, \cdots \vec{u}_n].$$

Changing coordinates from a basis \mathcal{B} of \mathbb{R}^n to another basis \mathcal{C} of \mathbb{R}^n

Suppose that $\mathcal{B} = \{\vec{u}_1, \vec{u}_2, \cdots, \vec{u}_n\}$ and $\mathcal{C} = \{\vec{v}_1, \vec{v}_2, \cdots, \vec{v}_n\}$ are bases. If \vec{w} is in \mathbb{R}^n , then we have

$$[\vec{w}]_{\mathcal{C}} = V^{-1}[\vec{w}]_{\mathrm{st}}$$
 and $[\vec{w}]_{\mathrm{st}} = U[\vec{w}]_{\mathcal{B}}$.

Substituting the second equation into the first, we get

$$[\vec{w}]_{\mathcal{C}} = V^{-1}U[\vec{w}]_{\mathcal{B}}, \text{ where } U = [\vec{u}_1, \vec{u}_2, \cdots \vec{u}_n] \text{ and } V = [\vec{v}_1, \vec{v}_2, \cdots \vec{v}_n].$$

It is hard to keep track of this, so we will use the following

Notation: the matrix of change of coordinates from a basis \mathcal{B} to a basis \mathcal{C} will be denoted by $[I]_{\mathcal{C},\mathcal{B}}$. It will be called **the matrix of change of basis from a basis** \mathcal{B} to a basis \mathcal{C} with the standard basis. We can then write

$$[\vec{w}]_{\mathcal{C}} = [I]_{\mathcal{C},\mathcal{B}} [\vec{w}]_{\mathcal{B}}, \text{ where } [I]_{\mathcal{C},\mathcal{B}} = V^{-1}U,$$

with $U = [\vec{u}_1, \vec{u}_2, \cdots \vec{u}_n]$ and $V = [\vec{v}_1, \vec{v}_2, \cdots \vec{v}_n].$

Note that the matrices of change of coordinates have the following intuitive rules. If you remember the first 3, things get easier:

- 1. $[I]_{st,\mathcal{B}} = U.$
- 2. $[I]_{\mathcal{B},\mathcal{C}} = ([I]_{\mathcal{C},\mathcal{B}})^{-1}$
- 3. If we have 3 bases, $[I]_{\mathcal{A},\mathcal{C}} = [I]_{\mathcal{A},\mathcal{B}} [I]_{\mathcal{B},\mathcal{C}}$.

For example, to remember the formula $[I]_{\mathcal{C},\mathcal{B}} = V^{-1}U$, you can write

$$[I]_{\mathcal{C},\mathcal{B}} = [I]_{\mathcal{C},\mathrm{st}} [I]_{\mathrm{st},\mathcal{B}} = ([I]_{\mathrm{st},\mathcal{C}})^{-1} [I]_{\mathrm{st},\mathcal{B}} = V^{-1}U.$$

Examples: Let $\mathcal{B} = \left\{ \begin{pmatrix} 1 \\ 2 \end{pmatrix}, \begin{pmatrix} 4 \\ 3 \end{pmatrix} \right\}$ and $\mathcal{C} = \left\{ \begin{pmatrix} -1 \\ 4 \end{pmatrix}, \begin{pmatrix} 2 \\ -7 \end{pmatrix} \right\}$. If the coordinates of \vec{w} in the basis \mathcal{B} are $\begin{pmatrix} -4 \\ 5 \end{pmatrix}$, find the coordinates of \vec{w} in the basis \mathcal{C} and in the standard basis. Solution: we know $[\vec{w}]_{\mathcal{B}} = \begin{pmatrix} -4 \\ 5 \end{pmatrix}$. We want to find $[\vec{w}]_{\mathcal{C}}$ and $[\vec{w}]_{\text{st}}$. $[\vec{w}]_{\text{st}} = [I]_{\text{st},\mathcal{B}} [\vec{w}]_{\mathcal{B}}$. Also, $[I]_{\text{st},\mathcal{B}} = \begin{pmatrix} 1 & 4 \\ 2 & 3 \end{pmatrix}$. Therefore $[\vec{w}]_{\text{st}} = \begin{pmatrix} 1 & 4 \\ 2 & 3 \end{pmatrix} \begin{pmatrix} -4 \\ 5 \end{pmatrix} = \begin{pmatrix} 16 \\ 7 \end{pmatrix}$. $[\vec{w}]_{\mathcal{C}} = [I]_{\mathcal{C},\mathcal{B}} [\vec{w}]_{\mathcal{B}} = [I]_{\mathcal{C},\text{st}} [I]_{rmst,\mathcal{B}} [\vec{w}]_{\mathcal{B}} = ([I]_{\mathcal{C},\text{st}})^{-1} [I]_{\mathcal{B},rmst} [\vec{w}]_{\mathcal{B}}$. Now, $[I]_{\mathcal{C},\text{st}} = \begin{pmatrix} -1 & 2 \\ 4 & -7 \end{pmatrix}$, so $([I]_{\mathcal{C},\text{st}})^{-1} = \begin{pmatrix} 7 & 2 \\ 4 & 1 \end{pmatrix}$. Therefore, $[I]_{\mathcal{C},\mathcal{B}} = \begin{pmatrix} 7 & 2 \\ 4 & 1 \end{pmatrix} \begin{pmatrix} 1 & 4 \\ 2 & 3 \end{pmatrix} = \begin{pmatrix} 11 & 34 \\ 6 & 19 \end{pmatrix}$, and $[\vec{w}]_{\mathcal{C}} = \begin{pmatrix} 11 & 34 \\ 5 \end{pmatrix} = \begin{pmatrix} -4 \\ 5 \end{pmatrix} = \begin{pmatrix} 126 \\ 71 \end{pmatrix}$.

Exercises

For the given bases, find the change of basis matrix from \mathcal{B} to \mathcal{C} .

•
$$\mathcal{B} = \left\{ \begin{pmatrix} 1\\3 \end{pmatrix}, \begin{pmatrix} -2\\-5 \end{pmatrix} \right\}, \mathcal{C} = \left\{ \begin{pmatrix} 4\\5 \end{pmatrix}, \begin{pmatrix} 3\\4 \end{pmatrix} \right\}$$

• $\mathcal{B} = \left\{ \begin{pmatrix} 1\\3\\2 \end{pmatrix}, \begin{pmatrix} -2\\-5\\0 \end{pmatrix}, \begin{pmatrix} -2\\0\\3 \end{pmatrix} \right\}, \mathcal{C} = \left\{ \begin{pmatrix} 1\\2\\0 \end{pmatrix}, \begin{pmatrix} 2\\0\\1 \end{pmatrix} \begin{pmatrix} 1\\1\\0 \end{pmatrix} \right\}$
• $\mathcal{B} = \left\{ \begin{pmatrix} -4\\3 \end{pmatrix}, \begin{pmatrix} 1\\-2 \end{pmatrix} \right\}, \mathcal{C} = \left\{ \begin{pmatrix} 3\\2 \end{pmatrix}, \begin{pmatrix} 2\\1 \end{pmatrix} \right\}$
• $\mathcal{B} = \left\{ \begin{pmatrix} 5\\2 \end{pmatrix}, \begin{pmatrix} 3\\-2 \end{pmatrix} \right\}, \mathcal{C} = \left\{ \begin{pmatrix} 0\\-4 \end{pmatrix}, \begin{pmatrix} 3\\4 \end{pmatrix} \right\}$