

# MATH 34 – Differential equations.

Third in-class test. Time allowed: two hours.

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**Directions:** Answer the following questions. The exam will be graded over 100 points; any points you get over 100, up to 110, will count as extra credit. The number to the left of each question is the number of points it is worth.

[25] 1. Answer the following short questions, justifying your answer:

a) Suppose that

- $y_1(t)$  and  $y_2(t)$  are independent solutions of the differential equation  $a\frac{d^2y}{dt^2} + b\frac{dy}{dt} + cy = 0$ ,
  - $y_P(t)$  is a solution of the differential equation  $a\frac{d^2y}{dt^2} + b\frac{dy}{dt} + cy = f(t)$ .
- Write down **three more solutions** of the differential equation  $a\frac{d^2y}{dt^2} + b\frac{dy}{dt} + cy = f(t)$ .

b) Determine if the following statement is true or false, justifying your answer: ‘A homogeneous  $2 \times 2$  linear system of differential equations always has  $x(t) = 0, y(t) = 0$  as an equilibrium solution’.

c) Write down a matrix whose eigenvalues are 0 and 3.

d) Find a homogeneous linear second degree differential equation with constant coefficients whose general solution is  $k_1e^{4t} + k_2e^{-3t}$ .

e) Determine if the following statement is true or false, justifying your answer, and giving a counterexample if the statement is false: ‘Every  $2 \times 2$  matrix has two different eigenvalues’

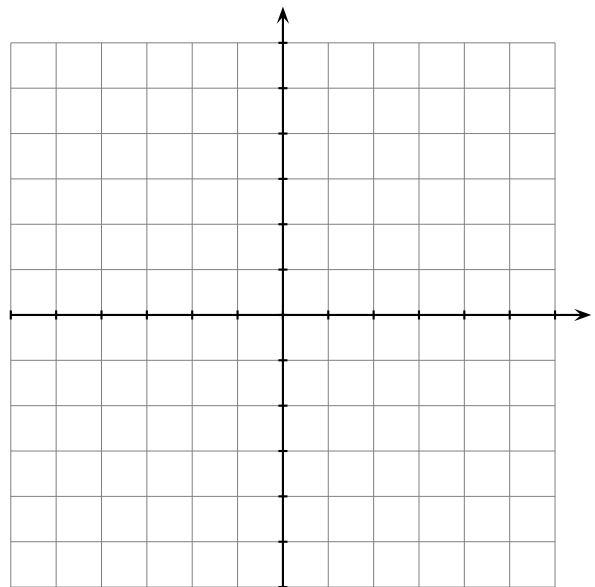
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[15] 2. For the system  $\frac{d\vec{Y}}{dt} = \begin{pmatrix} -4 & -2 \\ -1 & -3 \end{pmatrix} \vec{Y}$ .

a) Find the general solution.

b) Determine if the origin is a sink, a source, a saddle, a spiral sink, or a spiral source.

c) Sketch the phase plane, drawing carefully all the straight-line solutions (if any) and how the solutions approach (or leave, depending of the case) the origin (if they do). Please use the coordinate axes provided.

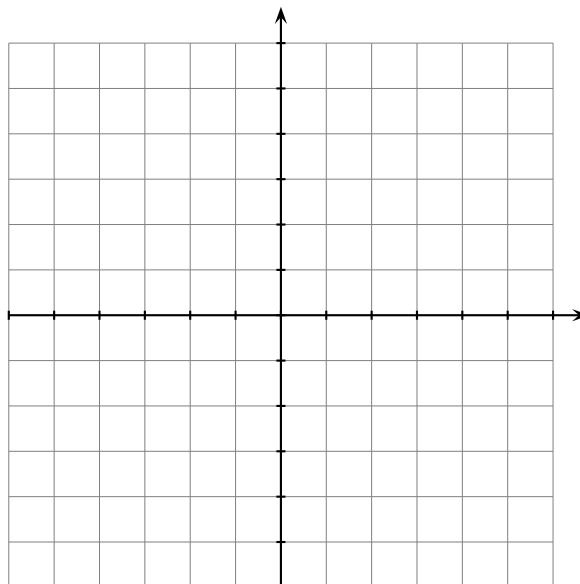


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[15] 3. Solve the initial-value problem  $\frac{d\vec{Y}}{dt} = \begin{pmatrix} -5 & 1 \\ -1 & -3 \end{pmatrix} \vec{Y}, \vec{Y}(0) = (-1, 2)$ .

[15] 4. For the system  $\frac{d\vec{Y}}{dt} = \begin{pmatrix} 2 & 2 \\ -4 & 6 \end{pmatrix} \vec{Y}$ .

- Find the general solution.
- Determine if the origin is a sink, a source, a saddle, a spiral sink, or a spiral source.
- Sketch the phase plane, drawing carefully all the straight-line solutions (if any) and how the solutions approach (or leave, depending of the case) the origin (if they do). Please use the coordinate axes provided.



[15] 5. Solve the initial value problem  $\frac{d^2y}{dt^2} + 9y = 27 \sin 6t$ ,  $y(0) = 0$ ,  $y'(0) = 0$

[15] 6. Consider the nonhomogeneous linear equation  $\frac{d^2y}{dt^2} + 4\frac{dy}{dt} + 13y = 5 \cos 2t$ ,

- Find the general solution of the associated homogeneous equation  $\frac{d^2y}{dt^2} + 4\frac{dy}{dt} + 13y = 0$ .
- Find a particular solution of the original nonhomogeneous equation and write it in the form  $A \cos(t - \phi)$  (or  $A \cos(t + \phi)$ ), where  $\phi$  is the phase given in degrees. Then write the general solution of the original equation.
- Briefly describe the long-term behavior of the solutions (i.e. the steady state solution).

[15] 7. [BONUS] The **Wronskian** of two vector functions  $(x_1(t), y_1(t))$  and  $(x_2(t), y_2(t))$  is defined by

$$W(t) := x_1(t)y_2(t) - x_2(t)y_1(t).$$

a) Compute  $\frac{dW}{dt}$  in terms of  $x_1, x_2, y_1$  and  $y_2$  and their derivatives.

b) Suppose that  $(x_1(t), y_1(t))$  and  $(x_2(t), y_2(t))$  are solutions of the system  $\begin{cases} \frac{dx}{dt} = ax + by \\ \frac{dy}{dt} = cx + dy \end{cases}$

Show that  $\frac{dW}{dt} = (a + d)W(t)$ .

c) Find the general solution of the equation  $dW/dt = (a + d)W(t)$ .

d) Use the previous items to show that if  $(x_1(t), y_1(t))$  and  $(x_2(t), y_2(t))$  are solutions of a linear system, and  $(x_1(0), y_1(0))$  and  $(x_2(0), y_2(0))$  are linearly independent vectors then, for any value of  $t$ ,  $(x_1(t), y_1(t))$  and  $(x_2(t), y_2(t))$  are also linearly independent vectors.

[Recall that two vectors  $(u_1, v_1)$  and  $(u_2, v_2)$  are linearly independent if  $u_1v_2 - u_2v_1 \neq 0$ .]