

Solutions HW 10

1) Done in HW 9, Ex 4.

2) Tu, 19.2:

$$\begin{aligned} F^*(u dv + v du) &= (x^2 + y^2) d(x^2 + y^2) + xy d(xy) \\ &= (x^2 + y^2)(2x dx + 2y dy) + xy(y dx + x dy) \\ &= (2x^3 + 3xy^2) dx + (2y^3 + 3x^2y) dy. \end{aligned}$$

Tu, 19.11.

The form df is identically 0 on M (since $f \equiv 0$ on M). It can be expressed as

$$df = f_x dx + f_y dy.$$

Thus, an "orthogonal" form will do the job:

$$\text{Let } \alpha = f_y dx - f_x dy.$$

Then, α is smooth, so $\alpha|_M$ is also smooth, and if $0 \neq a \frac{\partial}{\partial x} + b \frac{\partial}{\partial y} \in T_p M \subset T_p \mathbb{R}^2$, we have $df(a \frac{\partial}{\partial x} + b \frac{\partial}{\partial y}) = af_x + bf_y = 0$, which implies $a(f_y) - b(f_x) = 0$ since otherwise we would have $a \neq 0$.

Thus, $\alpha = f_y dx - f_x dy$ is a nowhere vanishing form in M .

b) On M , $df = f_x dx + f_y dy + f_z dz = 0$. If $f_x \neq 0$ and $f_y \neq 0$, this implies $-\frac{dx}{f_y} = \frac{dy}{f_x}$ on M . Wedging with dz (on M), we get $\frac{dz \wedge dx}{f_y} = \frac{dy \wedge dz}{f_x}$.

Similarly, if f_x and f_z or f_y and f_z are nonzero, we get a similar identity.
 This shows that, whenever defined,

$$\frac{dx \wedge dy}{f_z} = \frac{dy \wedge dz}{f_x} = \frac{dz \wedge dx}{f_y}.$$

Thus, let $\alpha = \begin{cases} \frac{dx \wedge dy}{f_z} & \text{if } f_z \neq 0 \\ \frac{dy \wedge dz}{f_x} & \text{if } f_x \neq 0 \\ \frac{dz \wedge dx}{f_y} & \text{if } f_y \neq 0 \end{cases}$

Then α is smooth and well defined.

To see that it is nonvanishing on M , assume WLOG, that $f_z \neq 0$ at some point. Then, if $\vec{u}, \vec{v} \in T_p M$, linearly independent, then

$$df(u) = f_x u_1 + f_y u_2 + f_z u_3 = 0 \Rightarrow$$

$$u_3 = -\frac{1}{f_z} (f_x u_1 + f_y u_2)$$

(similarly for \vec{v}).

This implies that, since the matrix $\begin{pmatrix} u_1 & u_2 & u_3 \\ v_1 & v_2 & v_3 \end{pmatrix}$ has rank 2, and since the last row is a linear combination of the first two, the first minor $u_1 v_2 - u_2 v_1 \neq 0$.

In particular,

$$\alpha(\vec{u}, \vec{v}) = \frac{1}{f_z} (u_1 v_2 - u_2 v_1) \neq 0.$$

This shows that α is nonvanishing.

(c) Use exactly the same procedure: show

$\alpha = (-1)^i \frac{dx^1 \wedge \dots \wedge \overset{i}{dx} \wedge \dots \wedge dx^n}{f(x)}$ independent of i ,
 and exactly the same calculation shows that it
 is nonvanishing on M .

3) Tu, 20.7. Recall Cartan's magic formula:

$$\mathcal{L}_X \omega = i_X(d\omega) + d(i_X \omega).$$

Also, note that $i_{fx} = f i_x$. Thus,

$$\begin{aligned} \mathcal{L}_{fx} \omega &= i_{fx}(d\omega) + d(i_{fx} \omega) = f i_x(d\omega) + d(f i_x \omega) \\ &= f i_x(d\omega) + f d(i_x \omega) + df \wedge i_x \omega \\ &= \underline{\mathcal{L}_x \omega + df \wedge i_x \omega}. \end{aligned}$$

Tu, 20.10 Compute:

$$\begin{aligned} i_X \omega &= \omega(X, \cdot) = x^2 dz + y^2 dy + xy dx - 2y dy - 2x dx \\ &= x(y-z) dx + y(y-z) dy + x^2 dz. \end{aligned}$$

(Notice that

$$\begin{aligned} &x dy \wedge dz \left(-y \frac{\partial}{\partial x} + x \frac{\partial}{\partial y}, \cdot \right) = \underbrace{x dy \wedge dz}_{0} \left(-y \frac{\partial}{\partial x} + x \frac{\partial}{\partial y}, \cdot \right) \\ &\quad + \underbrace{dy \wedge dz}_{1} \left(-y \frac{\partial}{\partial x} + x \frac{\partial}{\partial y}, \cdot \right) = x dy(\cdot) dz \left(-y \frac{\partial}{\partial x} + x \frac{\partial}{\partial y} \right) \\ &= x^2 dz(\cdot). \text{ The others one similar.} \end{aligned}$$

4) Tu, 21.5: $F(r, \theta) = (r \cos \theta, r \sin \theta)$.

We assume that the orientation in the domain is $[dr \wedge d\theta]$ and on the range is $dx \wedge dy$.

$$\begin{aligned} F^*(dx \wedge dy) &= d(r \cos \theta) \wedge d(r \sin \theta) \\ &= (\cos \theta dr - r \sin \theta d\theta) \wedge (\sin \theta dr + r \cos \theta d\theta) \\ &= r \cos^2 \theta dr \wedge d\theta + r \sin^2 \theta dr \wedge d\theta \\ &= r dr \wedge d\theta. \end{aligned}$$

Since $r > 0$, $[r dr \wedge d\theta] \neq [dr \wedge d\theta]$, so

F is orientation preserving for the assumed orientations.

21.9 Tu: Recall from a previous however that, on the tangent bundle, given charts $\tilde{\varphi}, \tilde{\psi}$, the determinant

$$\det(D(\tilde{\varphi} \circ \tilde{\psi}^{-1})) = (\det(D(\varphi \circ \psi^{-1})))^2 > 0.$$

This implies that $\{(\tilde{U}, \tilde{\varphi})\}$ (as constructed in class) is an oriented atlas, so TM is orientable.

5) There are several ways to do this. Here is one: Suppose $f^*\theta = 0$.
 First notice that $d\theta = dy \wedge dz$, and
 $\theta \wedge d\theta = dx \wedge dy \wedge dz$. Also, $f^*d\theta = df^*\theta = 0$.
 If X, Y are linearly independent vectors on M
 and Z is a vector on \mathbb{R}^3 ,

$$\begin{aligned}\theta \wedge d\theta(f_*X, f_*Y, Z) &= \theta(f_*X) d\theta(f_*Y, Z) - \\ &\quad - \theta(f_*Y) d\theta(f_*X, Z) + \theta(Z) d\theta(f_*X, f_*Y) \\ &= (f^*\theta)(X) d\theta(f_*Y, Z) - (f^*\theta)(Y) d\theta(f_*X, Z) \\ &\quad + \theta(Z) (f^*d\theta)(X, Y) = 0,\end{aligned}$$

Since $\theta \wedge d\theta = dx \wedge dy \wedge dz$, which is nondegenerate,
 this implies that f_*X, f_*Y, Z are linearly
 dependent for any choice of Z , which implies
 that f_*X, f_*Y are linearly dependent.
 Therefore, f_* cannot have rank 2, so it
 is not an immersion.

6) a) M^m orientable if there is $\omega \in \Omega^m M$ w/ $\omega_p \neq 0$ $\forall p$.
 b) If M and N orientable, then there are volume
 forms ω^M, ω^N in M and N . Then the form
 $(\omega^M \times \omega^N)(x^1, x^2, y^1, y^2) = \omega^M(x^1, x^2) \omega^N(y^1, y^2)$
 is always nonzero in $M \times N$. Therefore
 $M \times N$ is orientable.

Conversely, if ω is a volume form in $M \times N$, fix $q \in N$, let $y_1, \dots, y_n \in T_q N$ be a frame, For any point $p \in M$, the point $(p, q) \in M \times N$, and $T_{(p,q)}(M \times N) = T_p M \times T_q N$. Consider the m form in M given by

$$\omega_p^M(x_1, \dots, x_m) = \omega_{(p,q)}(x_1, \dots, x_m, y_1, \dots, y_n).$$

Then ω^M is a nonvanishing top form on M , so M orientable

A similar argument shows N orientable.

$$7a) [X, Y] = X(Y) - Y(X) = \left\{ X \frac{\partial}{\partial y} - Y \frac{\partial}{\partial x} \right\} - (x+y)(0) \\ = 0.$$

$$b) \text{ For } X, \begin{cases} x' = x \\ y' = -x \end{cases} \Rightarrow x = x_0 e^t, \quad y = -x_0 e^t + (y_0 + x_0). \\ = x_0(1 - e^t) + y_0$$

$$\text{Thus, } \varphi_t(x, y) = (x e^t, x(e^t - 1) + y).$$

$$\text{For } Y, \begin{cases} x' = 0 \\ y' = (x+y) \end{cases} \Rightarrow x = x_0, \quad y = (x_0 + y_0) e^t - x_0$$

$$\text{Thus, } \psi_t(x, y) = (x, x(e^t - 1) + y e^t)$$

$$c) \text{ Let } F(s, t) = \varphi_s \circ \psi_t(1, 0) = \varphi_s(1, e^{-t}) \\ = (e^s, 1 - e^s + e^{-t} - 1) = (e^s, e^t - e^s).$$

It is easy to see that $F_{*(1,0)}$ is nonsingular, so F is a local diffeomorphism and F^{-1} will give a local chart around $(1,0)$.

Also,

$$\frac{\partial F}{\partial s} = (e^s, e^s) = (F_1(s,t), F_2(s,t)) \\ = X_{F(s,t)}$$

and

$$\frac{\partial F}{\partial t} = (0, e^t) = (0, F_1(s,t) + F_2(s,t)) \\ = Y_{F(s,t)}.$$

8) We need to find $i_X(dx^1 \wedge \dots \wedge dx^n)$,

where $X_{(x^1, x^n)} = x^1 \frac{\partial}{\partial x^1} + \dots + x^n \frac{\partial}{\partial x^n}$.

In general,

$$i_X(dx^1 \wedge \dots \wedge dx^n) = dx^1(x) dx^2 \wedge \dots \wedge dx^n - dx^2(x) dx^1 \wedge dx^3 \wedge \dots \wedge dx^n \\ + \dots + (-1)^{n+1} dx^n(x) dx^1 \wedge \dots \wedge dx^{n-1}.$$

Since $dx^i(x) = x^i$, we get

$$i_X \omega = x^1 dx^2 \wedge \dots \wedge dx^n - x^2 dx^1 \wedge dx^3 \wedge \dots \wedge dx^n + (-1)^{n+1} dx^1 \wedge \dots \wedge dx^{n-1},$$

as claimed.

9) Using the orientation form ω^S of ex. 8, we get, since $\alpha(x', \gamma x'') = (-x', -\gamma x'')$,

$$\begin{aligned}\alpha^* \omega^S &= \sum_{i=1}^{n+1} (-x^i)(-1)^i dx'^1 \wedge \dots \wedge \overset{\wedge}{dx^i} \wedge \dots \wedge dx'^{n+1} \\ &= (-1)^{n+1} \sum_{i=1}^n x^i dx'^1 \wedge \dots \wedge \overset{\wedge}{dx^i} \wedge \dots \wedge dx'^{n+1} \\ &= (-1)^{n+1} \omega^S.\end{aligned}$$

thus, α is orientation preserving if n odd,
and reversing when n even.

(note that in ex. 8, the orientation form was for S^{n-1} , not for S^n .)

10) Consider $\pi: S^n \rightarrow \mathbb{RP}^n$, n odd.

Note that $\pi \circ \alpha = \pi$, so

$$\pi^* = \alpha^* \circ \pi^*$$

Now, $\pi^*: \Omega^n(\mathbb{RP}^n) \rightarrow \Omega^n(S^n)$.

Because π_x is onto, π^* is injective,
and the image of π^* consists of forms
 $\theta \in \Omega^n(S^n)$ satisfying $\alpha^* \theta = \theta$.

Thus, ω^S is in the image of π^* and
it has a single preimage $\tilde{\omega}_{\mathbb{RP}^n}$, which

Since $\pi^* \tilde{\omega}_{\mathbb{RP}^n} = \omega^S$, must be a volume form.

Thus, \mathbb{RP}^n is orientable.